



PIC16C621A → PIC16F627 Migration

DEVICE MIGRATIONS

This document is intended to describe the functional differences and the electrical specification differences that are present when migrating from one device to the next. Table 1 shows the considerations that must be taken into account when migrating from the PIC16C621A to the PIC16F627. Table 2 shows electrical and timing differences.

Note: This device has been designed to perform to the parameters of its data sheet. It has been tested to an electrical specification designed to determine its conformance with these parameters. Due to process differences in the manufacture of this device, this device may have different performance characteristics than its earlier version. These differences may cause this device to perform differently in your application than the earlier version of this device.

Note: The user should verify that the device oscillator starts and performs as expected. Adjusting the loading capacitor values and /or the oscillator mode may be required.

TABLE 1: PIC16C621A → PIC16F627 FUNCTIONAL DIFFERENCES

No.	Module	Differences from PIC16C621A	H/W	S/W	Prog.
1	Oscillator	ER osc mode	Yes	—	—
2	Oscillator	Dual Speed mode	Yes	—	—
3	Oscillator	EC osc mode	Yes	—	—
4	Oscillator	IntRC osc mode	Yes	—	—
5	USART	9-bit USART	Yes	—	—
6	Programming	Low Voltage Programming mode	—	—	Yes
7	Memory	RAM	—	—	Yes
8	Memory	EEPROM Data Memory	—	—	Yes

Legend: H/W - Issues may exist with regard to the application circuit.
 S/W - Issues may exist with regard to the user program.
 Prog. - Issues may exist with regard to programming.

OSCILLATOR MODULE

ER Mode

The PIC16F627 supports the new External Resistor oscillator mode. This mode differs from the traditional RC oscillator mode in that only a resistor to bias current is required. Designers should verify their oscillator design for suitability in the application before use. ER oscillator mode also supports Dual Speed mode.

EC Mode

The PIC16F627 supports the new External Clock-in mode. It is designed for usage in applications where a system clock is available. This mode provides a 1x clock directly to the PIC16F627 core. There is no gain stage in-line. Designers should verify their oscillator design for suitability in the application before use.

IntRC Mode

The PIC16F627 IntRC oscillator mode now supports Dual Speed mode also.

Dual Speed Mode

The PIC16F627 supports Dual Speed mode when configured in either ER or IntRC modes. This sub-mode of operation toggles between a fixed 37 kHz frequency and the frequency set by either ER or IntRC modes.

CONFIG Reg. bits Fosc<2:0>	Description	PCON Reg. bit OSCF	Result
111	ER mode w/clkout	1	ER bias'ed speed
111	ER mode w/clkout	0	37 kHz
110	ER mode w/o clkout	1	ER bias'ed speed
110	ER mode w/o clkout	0	37 kHz
101	IntRC w/clkout	1	4 MHz
101	IntRC w/clkout	0	37 kHz
100	IntRC w/o clkout	1	4 MHz
100	IntRC w/o clkout	0	37 kHz

USART MODULE

9-bit USART

The PIC16F627 USART now supports 9-bit mode. This mode is useful in multi-processor communications. When bits RX9 and ADEN in register RCSTA are set, multi-processor communication is enabled. The 9th bit is used to indicate whether address or data is being transmitted by the Master.

MEMORY ORGANIZATION MODULE

RAM

The PIC16F627 has 224 bytes of data RAM, while the PIC16C621A has 80.

EEPROM Data

The PIC16F627 has 128 bytes of EEPROM data memory.

PROGRAMMING MODULE

Low Voltage Programming Mode

The PIC16F627 supports Low Voltage Programming mode. When the LVP bit of the configuration word is asserted, placing a '1' on the RB4/PGM pin will instruct the part to enter Low Voltage Programming mode.

Note 1: While in this mode, the RB4 pin can no longer be used as a general purpose I/O pin.

2: VDD must be 5.0V ±10% during erase/program operations while in low voltage programming mode.

TABLE 2: PIC16C621A → PIC16F627 ELECTRICAL SPECIFICATION DIFFERENCES

Parm. No.	Sym.	Characteristic	PIC16C621A Data Sheet			PIC16F627 Data Sheet			Units	Conditions
			Min	Typ†	Max	Min	Typ†	Max		
D010	IDD	Supply Current (Note 1, 3)	—	0.4	1.2	—	—	0.7	mA	Fosc=4MHz, VDD=3.0V, WDT Disabled, XT osc mode (Note 3) Fosc=10MHz, VDD=3.0V, WDT Disabled, HS osc mode (Note 5)
			—	1.0	2.0	—	—	2.0	mA	
D023	ΔI _{WDT}	WDT Current (Note 4)	—	6.0	10	—	6.0	20	μA	VDD=4.0V (125°) VDD=4.0V VDD=4.0V
	ΔI _{COMP}	Comparator Current for each Comparator (Note 4)	—	—	12	—	—	25	μA	
	ΔI _{REF}	VREF Current (Note 4)	—	30	60	—	30	50	μA	
			—	80	135	—	—	135	μA	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C, unless otherwise stated. These parameters are for design guidance only and are not tested.

- Note 1:** The supply current is mainly a function of the operating voltage and frequency. Other factors such as I/O pin loading and switching rate, oscillator type, internal code execution pattern, and temperature also have an impact on the current consumption.
- The test conditions for all IDD measurements in active operation mode are:
 OSC1 = external square wave, from rail to rail; all I/O pins tri-stated, pulled to VDD,
 MCLR = VDD; WDT enabled/disabled as specified.
- 2: The power down current in SLEEP mode does not depend on the oscillator type. Power down current is measured with the part in SLEEP mode, with all I/O pins in hi-impedance state and tied to VDD or VSS.
 - 3: For RC osc configuration, current through Rext is not included. The current through the resistor can be estimated by the formula $I_r = V_{DD}/2R_{ext}$ (mA) with Rext in kΩ.
 - 4: The Δ current is the additional current consumed when this peripheral is enabled. This current should be added to the base IDD or IPD measurement.
 - 5: Commercial temperature range only.
 - 6: Includes EE static current. Does not include EE reads or writes.

TABLE 3: PIC16LC621A → PIC16LF627 ELECTRICAL SPECIFICATION DIFFERENCES

Parm. No.	Sym.	Characteristic	PIC16LC621A Data Sheet			PIC16LF627 Data Sheet			Units	Conditions
			Min	Typ†	Max	Min	Typ†	Max		
D010	IDD	Supply Current (Note 1, 3)	—	—	1.1	—	—	0.6	mA	FOSC=4MHz, VDD=2.5V, WDT Disabled, XT osc mode (Note 3)
D023	ΔI _{WDT}	WDT Current (Note 4)	—	—	—	—	6.0	15	μA	VDD=3.0V
			—	6.0	10	—	—	—	μA	VDD=4.0V
			—	—	12	—	—	—	μA	(125°)
	ΔI _{COMP}	Comparator Current for each Comparator (Note 4)	—	—	—	—	30	50	μA	VDD=3.0V
			—	30	60	—	—	—	μA	VDD=4.0V
	ΔI _{VREF}	VREF Current (Note 4)	—	—	—	—	—	135	μA	VDD=3.0V
—			80	135	—	—	—	μA	VDD=4.0V	

* These parameters are characterized but not tested.

† Data in "Typ" column is at 5.0V, 25°C, unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: The supply current is mainly a function of the operating voltage and frequency. Other factors such as I/O pin loading and switching rate, oscillator type, internal code execution pattern, and temperature also have an impact on the current consumption.

The test conditions for all IDD measurements in active operation mode are:

OSC1 = external square wave, from rail to rail; all I/O pins tri-stated, pulled to VDD,

MCLR = VDD; WDT enabled/disabled as specified.

- 2: The power down current in SLEEP mode does not depend on the oscillator type. Power down current is measured with the part in SLEEP mode, with all I/O pins in hi-impedance state and tied to VDD or VSS.
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- 4: The Δ current is the additional current consumed when this peripheral is enabled. This current should be added to the base IDD or IPD measurement.
- 5: Includes EE static current. Does not include EE reads or writes.

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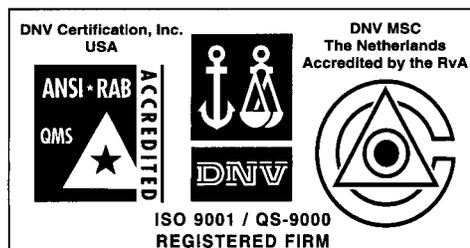
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2355 West Chandler Blvd.
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Technical Support: 480-792-7627
Web Address: <http://www.microchip.com>

Rocky Mountain

2355 West Chandler Blvd.
Chandler, AZ 85224-6199
Tel: 480-792-7966 Fax: 480-792-7456

Atlanta

500 Sugar Mill Road, Suite 200B
Atlanta, GA 30350
Tel: 770-640-0034 Fax: 770-640-0307

Austin - Analog

13740 North Highway 183
Building J, Suite 4
Austin, TX 78750
Tel: 512-257-3370 Fax: 512-257-8526

Boston

2 Lan Drive, Suite 120
Westford, MA 01886
Tel: 978-692-3848 Fax: 978-692-3821

Boston - Analog

Unit A-8-1 Millbrook Tarry Condominium
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Concord, MA 01742
Tel: 978-371-6400 Fax: 978-371-0050

Chicago

333 Pierce Road, Suite 180
Itasca, IL 60143
Tel: 630-285-0071 Fax: 630-285-0075

Dallas

4570 Westgrove Drive, Suite 160
Addison, TX 75001
Tel: 972-818-7423 Fax: 972-818-2924

Dayton

Two Prestige Place, Suite 130
Miamisburg, OH 45342
Tel: 937-291-1654 Fax: 937-291-9175

Detroit

Tri-Atria Office Building
32255 Northwestern Highway, Suite 190
Farmington Hills, MI 48334
Tel: 248-538-2250 Fax: 248-538-2260

Los Angeles

18201 Von Karman, Suite 1090
Irvine, CA 92612
Tel: 949-263-1888 Fax: 949-263-1338

New York

150 Motor Parkway, Suite 202
Hauppauge, NY 11788
Tel: 631-273-5305 Fax: 631-273-5335

San Jose

Microchip Technology Inc.
2107 North First Street, Suite 590
San Jose, CA 95131
Tel: 408-436-7950 Fax: 408-436-7955

Toronto

6285 Northam Drive, Suite 108
Mississauga, Ontario L4V 1X5, Canada
Tel: 905-673-0699 Fax: 905-673-6509

ASIA/PACIFIC

Australia

Microchip Technology Australia Pty Ltd
Suite 22, 41 Rawson Street
Epping 2121, NSW
Australia
Tel: 61-2-9868-6733 Fax: 61-2-9868-6755

China - Beijing

Microchip Technology Consulting (Shanghai)
Co., Ltd., Beijing Liaison Office
Unit 915
Bei Hai Wan Tai Bldg.
No. 6 Chaoyangmen Beidajie
Beijing, 100027, No. China
Tel: 86-10-85282100 Fax: 86-10-85282104

China - Chengdu

Microchip Technology Consulting (Shanghai)
Co., Ltd., Chengdu Liaison Office
Rm. 2401, 24th Floor,
Ming Xing Financial Tower
No. 88 TIDU Street
Chengdu 610016, China
Tel: 86-28-6766200 Fax: 86-28-6766599

China - Fuzhou

Microchip Technology Consulting (Shanghai)
Co., Ltd., Fuzhou Liaison Office
Rm. 531, North Building
Fujian Foreign Trade Center Hotel
73 Wusi Road
Fuzhou 350001, China
Tel: 86-591-7557563 Fax: 86-591-7557572

China - Shanghai

Microchip Technology Consulting (Shanghai)
Co., Ltd.
Room 701, Bldg. B
Far East International Plaza
No. 317 Xian Xia Road
Shanghai, 200051
Tel: 86-21-6275-5700 Fax: 86-21-6275-5060

China - Shenzhen

Microchip Technology Consulting (Shanghai)
Co., Ltd., Shenzhen Liaison Office
Rm. 1315, 13/F, Shenzhen Kerry Centre,
Renminnan Lu
Shenzhen 518001, China
Tel: 86-755-2350361 Fax: 86-755-2366086

Hong Kong

Microchip Technology Hongkong Ltd.
Unit 901-6, Tower 2, Metroplaza
223 Hing Fong Road
Kwai Fong, N.T., Hong Kong
Tel: 852-2401-1200 Fax: 852-2401-3431

India

Microchip Technology Inc.
India Liaison Office
Divyasree Chambers
1 Floor, Wing A (A3/A4)
No. 11, O'Shaughnessey Road
Bangalore, 560 025, India
Tel: 91-80-2290061 Fax: 91-80-2290062

Japan

Microchip Technology Japan K.K.
Benex S-1 6F
3-18-20, Shinyokohama
Kohoku-Ku, Yokohama-shi
Kanagawa, 222-0033, Japan
Tel: 81-45-471-6166 Fax: 81-45-471-6122

Korea

Microchip Technology Korea
168-1, Youngbo Bldg. 3 Floor
Samsung-Dong, Kangnam-Ku
Seoul, Korea 135-882
Tel: 82-2-554-7200 Fax: 82-2-558-5934

Singapore

Microchip Technology Singapore Pte Ltd.
200 Middle Road
#07-02 Prime Centre
Singapore, 188980
Tel: 65-334-8870 Fax: 65-334-8850

Taiwan

Microchip Technology Taiwan
11F-3, No. 207
Tung Hua North Road
Taipei, 105, Taiwan
Tel: 886-2-2717-7175 Fax: 886-2-2545-0139

EUROPE

Denmark

Microchip Technology Denmark ApS
Regus Business Centre
Lautrup høj 1-3
Ballerup DK-2750 Denmark
Tel: 45 4420 9895 Fax: 45 4420 9910

France

Arizona Microchip Technology SARL
Parc d'Activite du Moulin de Massy
43 Rue du Saule Trapu
Batiment A - 1er Etage
91300 Massy, France
Tel: 33-1-69-53-63-20 Fax: 33-1-69-30-90-79

Germany

Arizona Microchip Technology GmbH
Gustav-Heinemann Ring 125
D-81739 Munich, Germany
Tel: 49-89-627-144 0 Fax: 49-89-627-144-44

Germany - Analog

Lochhamer Strasse 13
D-82152 Martinsried, Germany
Tel: 49-89-895650-0 Fax: 49-89-895650-22

Italy

Arizona Microchip Technology SRL
Centro Direzionale Colleoni
Palazzo Taurus 1 V. Le Colleoni 1
20041 Agrate Brianza
Milan, Italy
Tel: 39-039-65791-1 Fax: 39-039-6899883

United Kingdom

Arizona Microchip Technology Ltd.
505 Eskdale Road
Winnersh Triangle
Wokingham
Berkshire, England RG41 5TU
Tel: 44 118 921 5869 Fax: 44-118 921-5820

08/01/01